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Data sheet for SINAMICS G120C

Article No. :

6SL3210-1KE32-4UF1



Figure similar

Client order no.
Order no. :
Offer no. :
Remarks :

Rated data			
Input			
Number of phases	3 AC		
Line voltage	380 480 V +10 % -20 %		
Line frequency	47 63 Hz		
Rated current (LO)	221.00 A		
Rated current (HO)	207.00 A		
Output			
Number of phases	3 AC		
Rated voltage	400V IEC	480V NEC ¹⁾	
Rated power (LO)	132.00 kW	150.00 hp	
Rated power (HO)	110.00 kW	125.00 hp	
Rated current (LO)	237.00 A		
Rated current (HO)	201.00 A		
Rated current (IN)	237.00 A		
Max. output current	402.00 A		
Pulse frequency	2 kHz		
Output frequency for vector control	0 240 Hz		
Output frequency for V/f control	0 550 Hz		

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200% base load current IH for 3 s, followed by 150% base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.90 0.95	
Offset factor $\cos \phi$	0.99	
Efficiency η	0.99	
Sound pressure level (1m)	68 dB	
Power loss	2,890.0 W	
Filter class (integrated)	Unfiltered	
Communication		

Communication

PROFINET, EtherNet/IP

ltem no. : Consignment no. : Project :

Inputs / outputs				
Standard digital inputs				
Number	6			
Switching level: $0 \rightarrow 1$	11 V			
Switching level: $1 \rightarrow 0$	5 V			
Max. inrush current	15 mA			
Fail-safe digital inputs				
Number	1			
Digital outputs				
Number as relay changeover contact	1			
Output (resistive load)	DC 30 V, 0.5 A			
Number as transistor	1			
Output (resistive load)	DC 30 V, 0.5 A			
Analog / digital inputs				
Number	1 (Differential input)			
Resolution	10 bit			
Switching threshold as digital input				
0→1	4 V			
1→0	1.6 V			
Analog outputs				
Number	1 (Non-isolated output)			
PTC/ KTY interface				
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$				
Closed-loop control techniques				
V/f linear / square-law / parameterizable	Yes			
V/f with flux current control (FCC)	Yes			
V/f ECO linear / square-law	Yes			
Sensorless vector control	Yes			

Vector control, with sensor No Encoderless torque control No Torque control, with encoder No

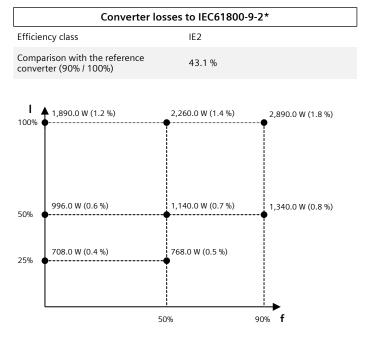
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Ambient conditions			
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.153 m³/s (5.403 ft³/s)		
Installation altitude	1,000 m (3,280.84 ft)		
Ambient temperature			
Operation	-20 40 °C (-4 104 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-40 70 °C (-40 158 °F)		
Relative humidity			
Max. operation	95 % RH, condensation not permitted		
Connections			
Signal cable			
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Line side			
Version	screw-type terminal		
Conductor cross-section	35.00 120.00 mm ² (AWG 2 AWG -3)		
Motor end			
Version	Screw-type terminals		
Conductor cross-section	35.00 120.00 mm ² (AWG 2 AWG -3)		
DC link (for braking resistor)			
Version	Screw-type terminals		
Conductor cross-section	35.00 120.00 mm ² (AWG 2 AWG -3)		
Line length, max.	10 m (32.81 ft)		
PE connection	Screw-type terminals		
Max. motor cable length			
Shielded	300 m (984.25 ft)		
Unshielded	450 m (1,476.38 ft)		
Μ	echanical data		
Degree of protection	IP20 / UL open type		
Frame size	FSF		
Net weight	61.50 kg (135.58 lb)		
Dimensions			
Width	305 mm (12.01 in)		
Height	708 mm (27.87 in)		
Depth	357 mm (14.06 in)		
	Standards		
Compliance with standards	UL, cUL, CE, C-Tick (RCM)		
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC		



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*calculated values

 $^{1)}\mbox{The}$ output current and HP ratings are valid for the voltage range 440V-480V