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Data sheet for SINAMICS G120C

Article No. :

6SL3210-1KE17-5UF1



Figure similar

Client order no. : Order no. : Offer no. : Remarks :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated current (LO)	9.50 A	
Rated current (HO)	8.20 A	
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC ¹⁾
Rated power (LO)	3.00 kW	4.00 hp
Rated power (HO)	2.20 kW	3.00 hp
Rated current (LO)	7.30 A	
Rated current (HO)	5.60 A	
Rated current (IN)	7.50 A	
Max. output current	11.20 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200% base load current IH for 3 s, followed by 150% base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor $\cos \phi$	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	52 dB	
Power loss	97.8 W	
Filter class (integrated)	Unfiltered	
Communication		

Communication

PROFINET, EtherNet/IP

ltem no. : Consignment no. : Project :

Inputs / outputs		
Standard digital inputs		
Number	6	
Switching level: $0 \rightarrow 1$	11 V	
Switching level: $1 \rightarrow 0$	5 V	
Max. inrush current	15 mA	
Fail-safe digital inputs		
Number	1	
Digital outputs		
Number as relay changeover contact	1	
Output (resistive load)	DC 30 V, 0.5 A	
Number as transistor	1	
Output (resistive load)	DC 30 V, 0.5 A	
Analog / digital inputs		
Number	1 (Differential input)	
Resolution	10 bit	
Switching threshold as digital input		
0→1	4 V	
1→0	1.6 V	
Analog outputs		
Number	1 (Non-isolated output)	
PTC/ KTY interface		
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$		
Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	

Vector control, with sensor No Encoderless torque control No Torque control, with encoder No

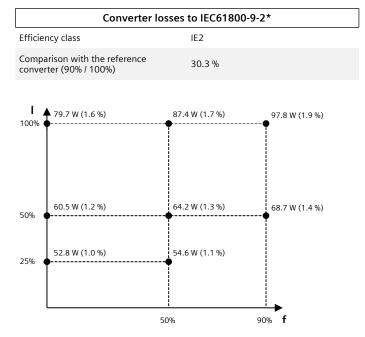
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Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.005 m³/s (0.177 ft³/s)	
Installation altitude	1,000 m (3,280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
Co	onnections	
Signal cable		
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)	
Line side		
Version	Plug-in screw terminals	
Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)	
Motor end		
Version	Plug-in screw terminals	
Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)	
DC link (for braking resistor)		
Version	Plug-in screw terminals	
Conductor cross-section	1.00 2.50 mm ² (AWG 18 AWG 14)	
Line length, max.	15 m (49.21 ft)	
PE connection	On housing with M4 screw	
Max. motor cable length		
Shielded	150 m (492.13 ft)	
Unshielded	150 m (492.13 ft)	
Мес	hanical data	
Degree of protection	IP20 / UL open type	
Frame size	FSA	
Net weight	1.70 kg (3.75 lb)	
Dimensions		
Width	73 mm (2.87 in)	
Height	196 mm (7.72 in)	
Depth	208 mm (8.19 in)	
S	itandards	
Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC	



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*calculated values

 $^{\rm 1)} {\rm The}$ output current and HP ratings are valid for the voltage range 440V-480V